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# Galerkin Method for Solving of Singular Integral Equation of Diffraction Problem\*

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## 1 The statement of the diffraction problem

Let  $P = \{x : 0 \leq x_1 \leq a, 0 \leq x_2 \leq b, 0 \leq x_3 \leq c\}$  be a resonator with perfectly conducting boundary. Let  $Q$  be a three-dimensional body, located in  $P$ .  $Q$  is characterized by tensor permittivity  $\hat{\epsilon}$  and constant permeability  $\mu_0$ . We suppose that components of  $\hat{\epsilon}$  are smooth functions in  $\bar{Q}$  and  $\left(\frac{\epsilon}{\epsilon_0} - \hat{I}\right)$  is invertible in  $\bar{Q}$ ;  $Q \cap \partial P = \emptyset$ . Let  $P/\bar{Q}$  be homogeneous and isotropic medium. Incident and diffraction fields depend on time variable as  $e^{-i\omega t}$ .

We will find electromagnetic diffraction fields  $E$  and  $H$ , satisfying Maxwell's equations in  $P \setminus \partial Q$ :

$$\begin{aligned} \text{rot } \vec{H} &= -i\omega \hat{\epsilon} \vec{E} + \vec{j}_E^0 \\ \text{rot } \vec{E} &= i\omega \mu_0 \vec{H} - \vec{j}_H^0 \end{aligned} \quad (1)$$

The complete field should have continuous tangent components at  $\partial Q$ :

$$\left[ \vec{n} \times \vec{E}^c \right] \Big|_{\partial Q} = \left[ \vec{n} \times \vec{H}^c \right] \Big|_{\partial Q} = 0$$

and must satisfy the following boundary condition:

$$\vec{E}_\tau^c|_{\partial P} = 0. \quad (2)$$

## 2 Integro-differential equations for the diffraction problem

We will express the solution of the stated problem in terms of vector potentials  $\vec{A}_E$  and  $\vec{A}_H$  [4]:

$$\begin{aligned} \vec{A}_E &= \int_Q \hat{G}_E(x, y) \vec{j}_E(y) dy, \quad \vec{A}_H = \int_Q \hat{G}_H(x, y) \vec{j}_H(y) dy, \\ \vec{E} &= i\omega \mu_0 \vec{A}_E - \frac{1}{i\omega \epsilon_0} \text{grad div } \vec{A}_E - \text{rot } \vec{A}_H, \\ \vec{H} &= i\omega \epsilon_0 \vec{A}_H - \frac{1}{i\omega \mu_0} \text{grad div } \vec{A}_H + \text{rot } \vec{A}_E. \end{aligned} \quad (3)$$

Here  $\vec{j}_E = \vec{j}_E^0 + \vec{j}_E^p$ ,  $\vec{j}_H = \vec{j}_H^0 + \vec{j}_H^p$ , ( $\vec{j}_E^p, \vec{j}_H^p$  are polarization currents).  $\hat{G}_E, \hat{G}_H$  are Green functions for Helmholtz equation, conforming to the arbitrary currents  $\vec{j}_E^0, \vec{j}_H^0$ .

$\hat{G}_E, \hat{G}_H$  are known [3] to have the form of diagonal tensors (the components of  $\hat{G}_E$  are written out below):

$$\begin{aligned} G_E^1 &= \sum_{n=0}^{\infty} \sum_{m=1}^{\infty} \frac{2\epsilon_n}{ab\gamma \text{sh}\gamma c} \cos\left(\frac{\pi n}{a} x_1\right) \sin\left(\frac{\pi m}{b} x_2\right) \cos\left(\frac{\pi n}{a} y_1\right) \sin\left(\frac{\pi m}{b} y_2\right) \begin{cases} \text{sh}\gamma x_3 \text{sh}\gamma(c - y_3), & x_3 < y_3 \\ \text{sh}\gamma y_3 \text{sh}\gamma(c - x_3), & x_3 > y_3 \end{cases} \\ G_E^2 &= \sum_{n=1}^{\infty} \sum_{m=0}^{\infty} \frac{2\epsilon_m}{ab\gamma \text{sh}\gamma c} \sin\left(\frac{\pi n}{a} x_1\right) \cos\left(\frac{\pi m}{b} x_2\right) \sin\left(\frac{\pi n}{a} y_1\right) \cos\left(\frac{\pi m}{b} y_2\right) \begin{cases} \text{sh}\gamma x_3 \text{sh}\gamma(c - y_3), & x_3 < y_3 \\ \text{sh}\gamma y_3 \text{sh}\gamma(c - x_3), & x_3 > y_3 \end{cases} \\ G_E^3 &= \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} \frac{4}{ab\gamma \text{sh}\gamma c} \sin\left(\frac{\pi n}{a} x_1\right) \sin\left(\frac{\pi m}{b} x_2\right) \sin\left(\frac{\pi n}{a} y_1\right) \sin\left(\frac{\pi m}{b} y_2\right) \begin{cases} \text{ch}\gamma x_3 \text{ch}\gamma(c - y_3), & x_3 < y_3 \\ \text{ch}\gamma y_3 \text{ch}\gamma(c - x_3), & x_3 > y_3 \end{cases} \end{aligned} \quad (4)$$

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Here  $\gamma = \sqrt{\left(\frac{\pi n}{a}\right)^2 + \left(\frac{\pi m}{b}\right)^2 - k_0^2}$  (the proper branch for square root is chosen as in [2], §2.3),  $\varepsilon_0 = 1$  and  $\varepsilon_n = 2$  for  $n = 1, 2, 3, \dots$ .

We can obtain the following integro-differential equations (under the condition  $\hat{\mu} = \mu_0 \hat{I}$  in  $P$ ):

$$\begin{aligned} \vec{E}(x) &= \vec{E}^0(x) + k_0^2 \int_Q \hat{G}_E \left[ \frac{\hat{\varepsilon}(y)}{\varepsilon_0} - \hat{I} \right] \vec{E}(y) dy + \text{grad div} \int_Q \hat{G}_E \left[ \frac{\hat{\varepsilon}(y)}{\varepsilon_0} - \hat{I} \right] \vec{E}(y) dy, \\ \text{and we have} \\ \vec{H}(x) &= \vec{H}^0(x) - i\omega \varepsilon_0 \text{rot} \int_Q \hat{G}_E \left[ \frac{\hat{\varepsilon}(y)}{\varepsilon_0} - \hat{I} \right] \vec{E}(y) dy, \quad x \in Q. \end{aligned} \quad (5)$$

We can extract singularity of Green function  $\hat{G}$ . Using Fourier transformation and interpolation polynomials we can obtain:

$$\hat{G}_E(x, y) = \frac{1}{4\pi} \frac{e^{ik_0|x-y|}}{|x-y|} \cdot \hat{I} + \text{diag}\{g_1(x, y), g_2(x, y), g_3(x, y)\},$$

where  $g_k$  are smooth functions.

### 3 Galerkin method

Let us introduce the following auxiliary function

$$\begin{aligned} \tilde{G}(x, y) &= - \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} \frac{4}{ab\gamma \text{sh}\gamma c} \sin\left(\frac{\pi n}{a}x_1\right) \sin\left(\frac{\pi m}{b}x_2\right) \sin\left(\frac{\pi n}{a}y_1\right) \sin\left(\frac{\pi m}{b}y_2\right) \times \\ &\quad \times \begin{cases} \text{sh}\gamma x_3 \text{sh}\gamma(c-y_3), & x_3 < y_3 \\ \text{sh}\gamma y_3 \text{sh}\gamma(c-x_3), & x_3 > y_3 \end{cases}. \end{aligned} \quad (6)$$

The derivatives of  $\tilde{G}$  are connected to the derivatives of  $G_E^i$  through the equalities:

$$\frac{\partial G_E^i}{\partial x_i} = \frac{\partial \tilde{G}}{\partial y_i}, \quad i = 1, 2, 3. \quad (7)$$

Before describing the method itself we should make some transformations of equation (5). Denoting  $\left(\frac{\hat{\varepsilon}(x)}{\varepsilon_0} - \hat{I}\right)^{-1}$  as  $\hat{\xi}$  and  $\left(\frac{\hat{\varepsilon}(x)}{\varepsilon_0} - \hat{I}\right) \vec{E}$  as  $\vec{J}$  we obtain the following equation

$$A\vec{J} := \hat{\xi} \vec{J}(x) - k_0^2 \int_Q \hat{G}_E \vec{J}(y) dy - \text{grad div} \int_Q \hat{G}_E \vec{J}(y) dy = \vec{E}_0(x) \quad (8)$$

We can write vector equation (8) as a system of three scalar equations:

$$\sum_{i=1}^3 \xi_{ii} J^i(x) - k_0^2 \int_Q G_E^l(x, y) J^l(y) dy - \frac{\partial}{\partial x_l} \text{div}_x \int_Q \hat{G}(x, y) \vec{J}(y) dy = E_0^l(x), \quad l = 1, 2, 3. \quad (9)$$

We will determine the components of approximate solution  $\vec{J}^{\frac{1}{2}}$  in the following way:

$$\vec{J}^1 = \sum_{k=1}^N a_k f_k^1(x), \quad \vec{J}^2 = \sum_{k=1}^N b_k f_k^2(x), \quad \vec{J}^3 = \sum_{k=1}^N c_k f_k^3(x), \quad (10)$$

where  $f_k^i$  are basis "hat"-functions dependent essentially on  $x^i$ . The explicit form of  $f_k^1$  is given below.

Let  $Q$  be a parallelepiped:  $Q = \{x : a_1 \leq x^1 \leq a_2, b_1 \leq x^2 \leq b_2, c_1 \leq x^3 \leq c_2\}$ ,  $Q \subset P$ . We will cover  $Q$  with smaller parallelepipeds

$$\begin{aligned} \Pi_{klm}^1 &= \{x : x_{k-1}^1 \leq x^1 \leq x_{k+1}^1, x_l^2 \leq x^2 \leq x_{l+1}^2, x_m^3 \leq x^3 \leq x_{m+1}^3\} \\ x_k^1 &= a_1 + \frac{a_2 - a_1}{n} k, \quad x_l^2 = b_1 + 2 \frac{b_2 - b_1}{n} l, \quad x_m^3 = c_1 + 2 \frac{c_2 - c_1}{n} m; \end{aligned} \quad (11)$$

where  $k = 1, \dots, n-1$ ;  $l, m = 0, 1, \dots, \frac{n}{2}-1$ .

Denoting  $(x_k - x_{k-1})$  as  $h^1$  we get the formulas for  $f_{klm}^1$ :

$$f_{klm}^1 = \begin{cases} \frac{x^1 - x_{k-1}^1}{x_k^1 - x_{k-1}^1}, & \text{if } x^1 \in [x_{k-1}^1; x_k^1] \text{ and } x \in \Pi_{klm}^1 \\ \frac{x_{k+1}^1 - x^1}{x_{k+1}^1 - x_k^1}, & \text{if } x^1 \in [x_k^1; x_{k+1}^1] \text{ and } x \in \Pi_{klm}^1 \\ 0, & \text{if } x \notin \Pi_{klm}^1 \end{cases} \quad (12)$$

or

$$f_{klm}^1 = \begin{cases} 1 - \frac{1}{h^1}|x^1 - x_k^1|, & \text{if } x \in \Pi_{klm}^1 \\ 0, & \text{if } x \notin \Pi_{klm}^1 \end{cases} \quad (13)$$

Functions  $f_{klm}^2$  and  $f_{klm}^3$  should be determined by similar formulas. Since

$$f_{klm}^1|_{x^1 \in \{x_{k-1}^1, x_{k+1}^1\}} = 0, \quad f_{klm}^2|_{x^2 \in \{x_{i-1}^2, x_{i+1}^2\}} = 0, \quad f_{klm}^3|_{x^3 \in \{x_{m-1}^3, x_{m+1}^3\}} = 0, \quad (14)$$

every component of approximate vector solution vanishes at some side of  $Q$ . However the constructed set of basis functions does satisfy the necessary approximation condition.

Introducing total enumeration for basis functions we get

$$f_k^1, f_k^2, f_k^3; \quad k = 1, \dots, N,$$

where  $N = \frac{1}{4}(n^3 - n^2)$ .

It is convenient to represent the augmented matrix for determining unknown coefficients  $a_k, b_k, c_k$  in block form:

$$\left( \begin{array}{ccc|c} A_{11} & A_{12} & A_{13} & B_1 \\ A_{21} & A_{22} & A_{23} & B_1 \\ A_{31} & A_{32} & A_{33} & B_1 \end{array} \right) \quad (15)$$

where columns  $B_k$  and matrices  $A_{kl}$  are determined by formulas:

$$B_k^i = (E_0^k, f_i^k); \quad (16)$$

$$A_{kl}^{ij} = (\xi_{kl} f_j^i, f_i^k) - \delta_{kl} k_0^2 \left( \int_Q G_E^k(x, y) f_j^i(y) dy, f_i^k(x) \right) - \left( \frac{\partial}{\partial x_k} \int_Q \frac{\partial}{\partial x_l} G_E^k(x, y) f_j^i(y) dy, f_i^k(x) \right), \quad (17)$$

$k = 1, 2, 3$ ;  $i = 1, \dots, N$ .  $(f, g)$  determines the scalar product in  $L_2$ ,  $(f, g) = \int_Q f(x)g(x)dx$ .

Applying the formulas of integration by parts to both internal and external integrals and taking into account (7) and (14) we obtain:

$$A_{kl}^{ij} = \int_{\Pi_j^i \cap \Pi_k^i} \xi_{kl} f_j^i(x) f_i^k(x) dx - \delta_{kl} k_0^2 \int_{\Pi_k^i} \int_{\Pi_j^i} G_E^k(x, y) f_j^i(y) f_i^k(x) dy dx - \int_{\Pi_k^i} \int_{\Pi_j^i} \tilde{G}(x, y) \frac{\partial}{\partial x_l} f_j^i(y) \frac{\partial}{\partial x_k} f_i^k(x) dy dx. \quad (18)$$

## References

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- [3] Samohin, A.B., "Integral Equations and Iteration Methods in Electromagnetic Scattering", Radio & Sviaz, Moscow, 1998. (in Russian)